

neptronic

Networkable VAV Controller

Specification and Installation Instructions

Models

EVCB14NITOS (0 TRIACS / pressure independent)
EVCB14NIT2S (2 TRIACS / pressure independent)
EVCB14NIT4S (4 TRIACS / pressure independent)
EVCB14NIT4X* (4 TRIACS / independent / external

motor)

EVCB14NDT4X* (4 TRIACS / dependent / external motor)
EVCB14NDT4S (4 TRIACS / pressure dependent)
EVCB14NIT0SF (0 TRIACS / independent / feedback)
EVCB14NIT4SF (4 TRIACS / independent / feedback)

* For use with either floating or modulating actuators

TRL Series Digital Room Sensor

TRL54 (With temperature sensor)

TDU Series Digital Room Sensor

TDU00 (Vertical Grey LCD, white enclosure)
TDU30 (Vertical Black LCD, black enclosure)
TDU60 (Vertical Black LCD, white enclosure)

TDU10 (Horizontal Grey LCD, white enclosure)
TDU40 (Horizontal Black LCD, black enclosure)
TDU70 (Horizontal Black LCD, white enclosure)

Description

The EVCB Series is a combination controller and digital room sensor with support for networked communications via the BACnet MS/TP or Modbus protocol. The Networkable VAV Controller is designed for simple and accurate control of any variable air volume box in a number of zone control configurations. Its field configurable algorithms enable versatile implementation of required control sequences.

Features

- Field configured VAV algorithms, inputs and outputs
- Built-in actuator, 70 lb-in. (select models, not available on EVCB14NIT4X and EVCB14NDT4X)
- Control external actuators using analog (0-10Vdc, adjustable) or floating signals with feedback (models EVCB14NIT4X and EVCB14NDT4X)
- On board differential pressure sensor (select models)
- Simple air balancing and commissioning via digital room sensor
- Automatically sets operation mode to pressure dependent or independent based on the presence of air flow
- Select direction on analog outputs
- Configurable PI (Proportional-Integral) function
- Independent, configurable proportional control band and dead band per ramp
- Selectable internal or external temperature sensor (10ΚΩ)
- External CO2 sensor input with integrated logic
- Changeover by contact or external temperature sensor
- Internal and external temperature sensor calibration
- Optional potentiometer feedback for increased precision of actuator position
- Freeze protection
- Removable, raising clamp, non-strip terminals

Operational Features

- Backlit LCD with simple icon and text driven menus
- · Select digital room sensor's default display
- Network service port via on-board mini USB connector
- Manual night set back or no occupancy override
- Multi level lockable access menu and setpoint
- Selectable Fahrenheit or Celsius scale
- 3-wire connection to controller and 4 push buttons



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EVCB Series

TRL54





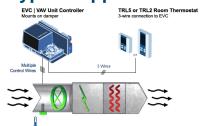
TDU00 / TDU30 / TDU60 Series

TDU10 / TDU40 / TDU70 Series

Applications

- Single duct, cooling only
- Single duct cooling and/or heating
- Up to 4 stage reheat and/or cool
- Up to 4 On/Off heat and/or cool
- Up to 4 time proportioned (TPM) heat or reheat
- Up to 2 analog (0-10Vdc) reheat and/or cool
- Up to 2 floating heat and/or cool
- Pressure dependent or pressure independent
- · With or without auto changeover
- Supply/exhaust (requires an additional EVC)

Typical Application



Network Communication

- BACnet MS/TP or Modbus communication port
- Select MAC address via DIP switch or via network
- Automatic baud rate detection

BACnet MS/TP®

- Automatic device instance configuration
- Copy & broadcast configuration via digital room sensor menu or via BACnet to other controllers
- BACnet scheduler
- Firmware upgradeable via BACnet
- Support for COV (change of value)

Modbus

- Modbus @ 9600, 19200, 38400 or 57600 bps
- RTU Slave, 8 bits (configurable parity and stop bits)
- Connects to any Modbus master

EVCB14N-TRL54-V508-231219-ESA Page | 1



Specification and Installation Instructions

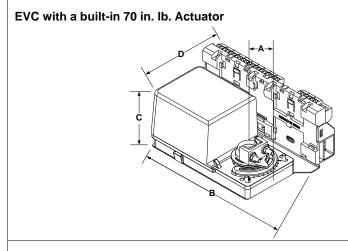
Controller Specifications

Description	EVCB Series
Torque	70 in.lb. [8 Nm] at rated voltage
Power consumption	10 VA max
Running time through 90°	90 seconds
Power supply	22 to 26 Vac 50/60 Hz
Inputo	2 Universal inputs (Thermistor 10KΩ Type 3, digital 24Vac/dry contact, or 0-10Vdc)
Inputs	2 digital inputs
	2 analog outputs (0-10 Vdc or 2-10Vdc; selectable)
Outputs	Up to 4 TRIAC outputs 24 Vac, 500mA max thermal fuse in series with each TRIAC output (on/off, pulse, or 2 floating outputs)
Real Time Clock	Real-time clock (RTC) with super capacitor backup (approximately 3 days)
BACnet	BACnet® MS/TP @ 9600, 19200, 38400 or 76800 bps (BAS-C)
Modbus	Modbus RTU slave @ 9600, 19200, 38400 or 57600. Selectable parity and stop bit configuration: No parity, 2 stop bit Even parity, 1 stop bit Odd parity, 1 stop bit
Communication connection	Low capacitance, EIA RS-485, 22 or 24 AWG shielded twisted pair multi-strand cables (Belden 9841 or equivalent).
Digital room sensor connection	Insulated 3 core multi-strand 22 or 24 AWG cable. Maximum 50ft (15m) between controller and digital room sensor.
Electrical connection	Insulated 2 core 0.8 mm ² [18 AWG] minimum power cable.
Operating temperature	0°C to 50°C [32°F to 122°F]
Storage temperature	-30°C to 50°C [-22°F to 122°F]
Relative Humidity	5 to 95% non condensing
Weight	1.26 kg. [2.8 lb]



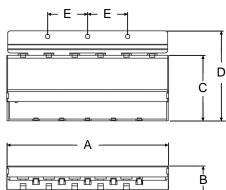
The actuator performs an auto-stroke on power up. When changing the actuator adjustment screws, cycle power to initiate the auto-stroke. Auto-stroke is not available on EVC pressure independent without feedback.

Dimensions



A = 1.50" | 39mm B = 7.25" | 185mm C = 3.25" | 83mm D = 5.50" | 140mm

EVC with a separate 180 in. lb. Actuator



A = 7.20" | 183mm B = 1.23" | 31mm C = 2.93" | 74mm D = 4.02" | 102mm E = 1.78" | 45mm



Specification and Installation Instructions

Digital Room Sensor Specifications

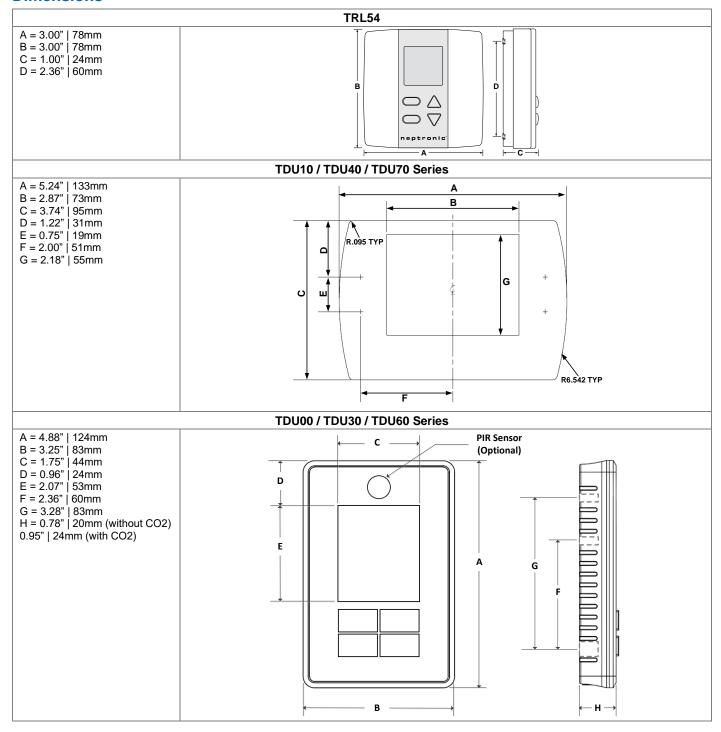
Description	TRL54 and TDU Series						
Temperature Sensor (TRL54 a	nd TDU)						
Setpoint range	10°C to 40°C [50°F to 104°F]						
Control accuracy	Temperature: ±0.4°C [0.8°F]						
Display resolution	±0.1°C [0.2°F]						
Humidity Sensor (TDU models	s with Humidity Sensors)						
Sensor range	to 95%RH						
Display resolution	0.1%						
CO ₂ Sensor (TDU models with	n CO₂ Sensors)						
Operating principle	Self-calibrating, Non-Dispersive Infrared (NDIR)						
Sensor Range	0 to 2000 ppm						
Setpoint range	100 to 2000 ppm						
Accuracy	±30 ppm ±3% of reading						
Response time	2 minutes by 90%						
Display resolution	1 ppm						
PIR Motion Sensor (TDU00 / T	DU 30 / TDU60 models with PIR Sensor)						
Operating Principle	Passive Infrared (PIR)						
Detection Angle	100°						
Detection Distance	4m [13ft]						
Detection Area	4m (13ft) 100°						
VOC Sensor (TDU00 / TDU30 /	/ TDU60 models with VOC Sensor)						
Operating Principle	Self-calibrating, Non-Dispersive Infrared (NDIR)						
Sensor Range	0-1000 ppb isobutylene equivalent tVOCs						
Response Time	<5 seconds for tVOC						
Start up Time	15 minutes						
Other							
Electrical connection	3 wires to VAV controller and 2 wires to BACnet/Modbus network 0.8 mm ² [18 AWG] minimum						
Network service port	Mini USB connector						
Power supply	24Vac						
Power consumption	1VA						
Operating temperature	0°C to 50°C [32°F to 122°F]						
Storage temperature	-30°C to 50°C [-22°F to 122°F]						
<u> </u>							
Relative humidity	5 to 95 % non condensing						
Relative humidity Enclosure protection	IP 30 (EN 60529)						

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Specification and Installation Instructions

Dimensions





Specification and Installation Instructions

TDU Models

Horizontal Model #	Temp	RH	CO ₂
TDU10-100 TDU40-100 TDU70-100	•		
TDU10-101 TDU40-101 TDU70-101	•	•	
TDU10-102 TDU40-102 TDU70-102	•	•	•
TDU10-103 TDU40-103 TDU70-103	•		•







TDU10 Series

TDU40 Series

TDU70 Series

Vertical Model #	Temp	RH	CO ₂	PIR	voc
TDU00-100 TDU30-100 TDU60-100	•				
TDU00-101 TDU30-101 TDU60-101	•	•			
TDU00-102 TDU30-102 TDU60-102	•	•	•		
TDU00-103 TDU30-103 TDU60-103	•		•		
TDU00-104 TDU30-104 TDU60-104	•			•	
TDU00-105 TDU30-105 TDU60-105	•	•		•	
TDU00-106 TDU30-106 TDU60-106	•	•	•		•
TDU00-107 TDU30-107 TDU60-107	•	•	•	•	•
TDU00-108 TDU30-108 TDU60-108	•	•	•	•	







TDU00 Series

TDU30 Series

TDU60 Series



Specification and Installation Instructions

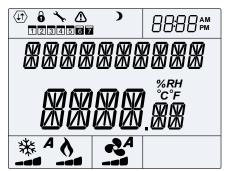
Interface

TRL54



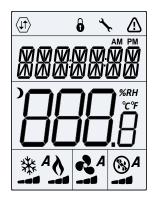
*A	Cooling ON A: Automatic	4	Programming mode (Technician setting)	\triangle	Alarm status
I O A	Heating ON A: Automatic	6	Menu set-up Lock)	Energy saving mode
MIN MAX	Minimum/Maximum	°C _{or} °F	°C: Celsius scale °F: Fahrenheit scale		

TDU10 / TDU40 / TDU70 Series



<u>(11)</u>	Network Communication	6	User Lock	4		nming Mode cian Setting)
	Alarm Status)	Energy Saving Mode (NSB/OCC)	123	4567	Schedule
88:88 [§] M	Time	ррт	Parts Per Million	°C °F %RH	°F: Fahr	lsius Scale enheit Scale : Humidity
А	Automatic Mode	辮	Cooling	7		Heating
				€.		Fan

TDU00 / TDU30 / TDU60 Series



$\langle \downarrow \uparrow \rangle$	Network Communication	6	User Lock	*	Programming Mode (Technician Setting)
A	Alarm Status)	Energy Saving Mode (NSB/OCC)	AM PM	Time
°C °F %RH	°C: Celsius Scale °F: Fahrenheit Scale %RH: Humidity	А	Automatic Mode	**	Cooling
7	Heating	2	Fan		



Specification and Installation Instructions

Mechanical Installation

- Manually close the damper blades and position the actuator to 0° or 90°.
- 2. Slide the actuator onto the shaft.
- 3. Tighten the nuts on the "U" bolt to the shaft with an 8mm wrench to a torque of 60 in-lb [6.7 Nm].
- Slide the mounting bracket under the actuator. Ensure free movement of the slot at the base of the actuator. Place the bracket pin at mid distance of the slot.
- Affix the bracket to the ductwork with #8 self-tapping screws.

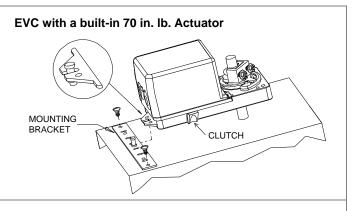


Do not press the clutch when the actuator is powered.

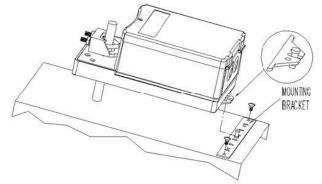
- Manually close the damper blades and position the actuator to 0° or 90°.
- 2. Slide the actuator onto the shaft.
- 3. Tighten the nuts on the "U" bolt to the shaft with an 8mm wrench to a torque of 150 in.lb. [17 Nm].
- Slide the mounting bracket under the actuator. Ensure free movement of the slot at the base of the actuator. Place the bracket pin at mid distance of the slot.
- Affix the bracket to the ductwork with #8 self-tapping screws.
- Connect the cable from the EVC to the terminal in the actuator as shown.



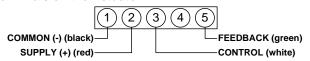
Do not press the clutch when the actuator is powered.



EVC with a separate 180 in. lb. Actuator

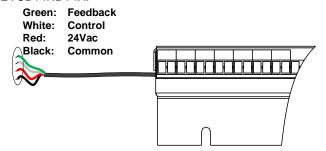


Terminals on the Actuator



Signal cable from EVC controller (models EVCB14NIT4X and EVCB14NDT4X)

Use to connect the external motor on EVCB14NIT4X and EVCB14NDT4X.







Specification and Installation Instructions

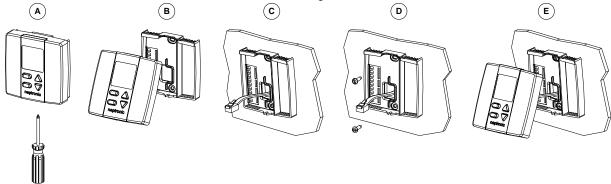
Mounting Instructions

TRL54



CAUTION: Remove power to avoid a risk of malfunction.

- A. Remove the captive screw that's holding the base and the front cover of the unit together.
- B. Lift the front cover of the unit to separate it from the base.
- C. Pull all wires through the holes in the base.
- D. Secure the base to the wall using wall anchors and screws (supplied). Make the appropriate connections.
- E. Mount the control module on the base and secure using the screw.

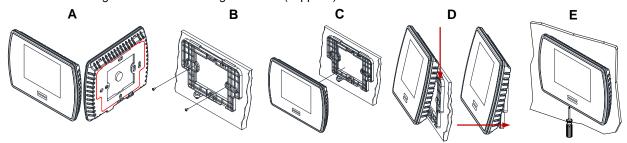


TDU10 / TDU40 / TDU70 Series



CAUTION: Remove power to avoid a risk of malfunction.

- A. Remove the wall mounting plate (highlighted) from the back of the digital room sensor.
- B. Install the mounting plate on the gang box.
- C. Pull the wires through the base hole and make the appropriate connections.
- D. Mount the digital room sensor onto the wall plate. To mount it correctly, place the top of the digital room sensor on the mounting plate first and push it into the grooves to snap it into place.
- E. Secure the digital room sensor using the screw (supplied).

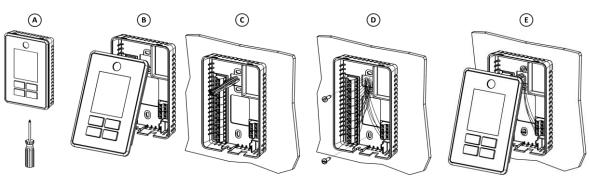


TDU00 / TDU30 / TDU60 Series



CAUTION: Remove power to avoid a risk of malfunction.

- A. Remove the captive screw that's holding the base and the front cover of the unit together.
- B. Lift the front cover of the unit to separate it from the base.
- C. Pull all wires through the holes in the base.
- D. Secure the base to the wall using wall anchors and screws (supplied). Make the appropriate connections.
- E. Mount the control module on the base and secure using the screw.





Specification and Installation Instructions

BACnet or Modbus Address DIP Switch (DS1)

MAC address for communication, are selectable by DIP switch using binary logic. If you do not change device instance in program mode, it will be automatically modified according to the MAC address.



Note: Avoid using addresses above 246 when selecting Modbus MAC address.

MAC Address	DS.1 = 1	DS.2 = 2	DS.3 = 4	DS.4 = 8	DS.5 = 16	DS.6 = 32	DS.7 = 64	DS.8 = 128	Default Device Instance
0	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	153000
1	ON	OFF	OFF	OFF	OFF	OFF	OFF	OFF	153001
2	OFF	ON	OFF	OFF	OFF	OFF	OFF	OFF	153002
3	ON	ON	OFF	OFF	OFF	OFF	OFF	OFF	153003
4	OFF	OFF	ON	OFF	OFF	OFF	OFF	OFF	153004
126	OFF	ON	ON	ON	ON	ON	ON	OFF	153126
127	ON	ON	ON	ON	ON	ON	ON	OFF	153127

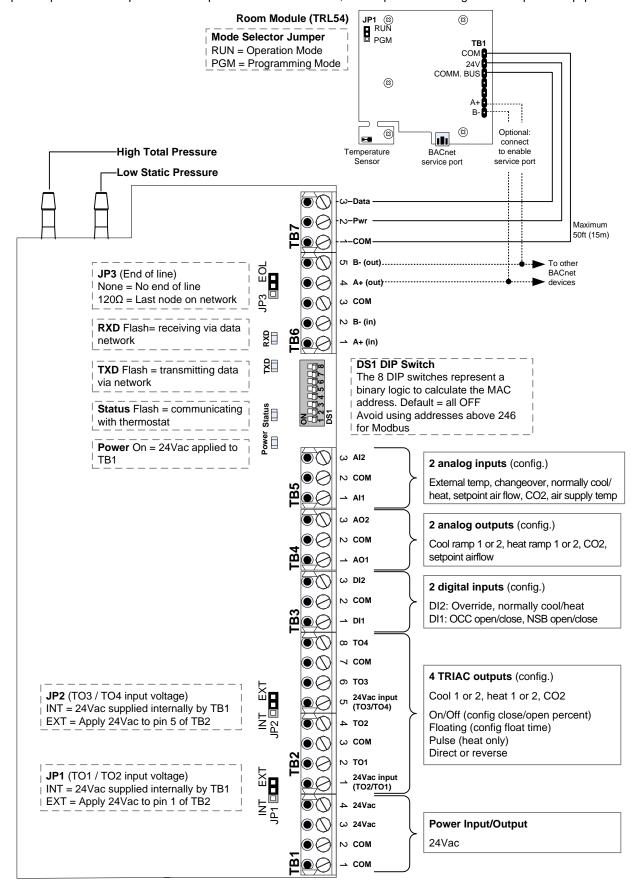
^{*} Slave addresses available by setting DS.8 to ON



Specification and Installation Instructions

Wiring

We strongly recommend that all Neptronic products be wired to a separate grounded transformer and that transformer shall service only Neptronic products. This precaution will prevent interference with, and/or possible damage to incompatible equipment.



PCB Drawings

neptronic[®]

Networkable VAV Controller

Specification and Installation Instructions

TRL54 Digital Room Sensor

3 wire cable (TB1 #1, 2 & 3)

Connect TB1 #6 (A+) & #7 (B-) to EVCB to enable the BACnet service port.

É Connecting strip PGM СОМ Mode selector 24V сомм. BUS (3)(≅) Al1 ♣ DI1 c A+ 6 Temperature **BACnet** sensor service port (3)nn [A] nr

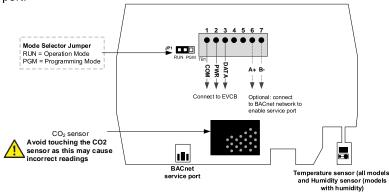
Mode Selection (JP1)

JP1 RUN PGM	Jumper (JP1) on RUN: Digital room sensor is in Operation Mode. Digital room sensor must be set in this mode to operate properly. If not locked, setpoint and control mode (Heating & Cooling ON, Cooling only ON or Heating only ON) can be modified by end user.
JP1 RUN PGM	Jumper (JP1) on PGM: Digital room sensor is set in <u>Programming Mode</u> . Refer to following section about all settings description

TDU10 / TDU40 / TDU70 Series Digital Room Sensor

3 wire cable (TB1 #1, 2 & 3)

Connect TB1 #6 (A+) & #7 (B-) to EVCB to enable the BACnet service port.



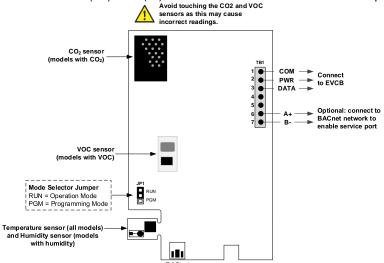
Mode Selection (JP1)

JP1 RUN	RUN: Digital room sensor is in Operation Mode. Digital room sensor must be set in this mode for normal system operation. If not locked, setpoint and control mode can be changed by the end user.
JP1 RUN PGM	PGM: Digital room sensor is set in Programming Mode. Refer to the following sections for more details.

TDU00 / TDU30 / TDU60 Series Digital Room Sensor

3 wire cable (TB1 #1, 2 & 3)

Connect TB1 #6 (A+) & #7 (B-) to EVCB to enable the BACnet service port.



Mode Selection (JP1)

JP1 RUN PGM	RUN: Digital room sensor is in Operation Mode. Digital room sensor must be set in this mode for normal system operation. If not locked, setpoint and control mode can be changed by the end user.
JP1 □ RUN □ PGM	PGM: Digital room sensor is set in Programming Mode. Refer to the following sections for more details.

Access to Menus



Specification and Installation Instructions

The menu overviews and options are the same for both TRL54 and TDU digital room sensors. However, the action button or the button used to access the menus and save changes is different in the digital room sensors. Use the following menu overviews with the appropriate action button as per your digital room sensor.

Action Buttons on Digital Room Sensor

Action B	utton	Task	
TRL54	TDU		
*		Press to access the programming menus and save any changes.	
4		Press to return to the previous step without saving.	

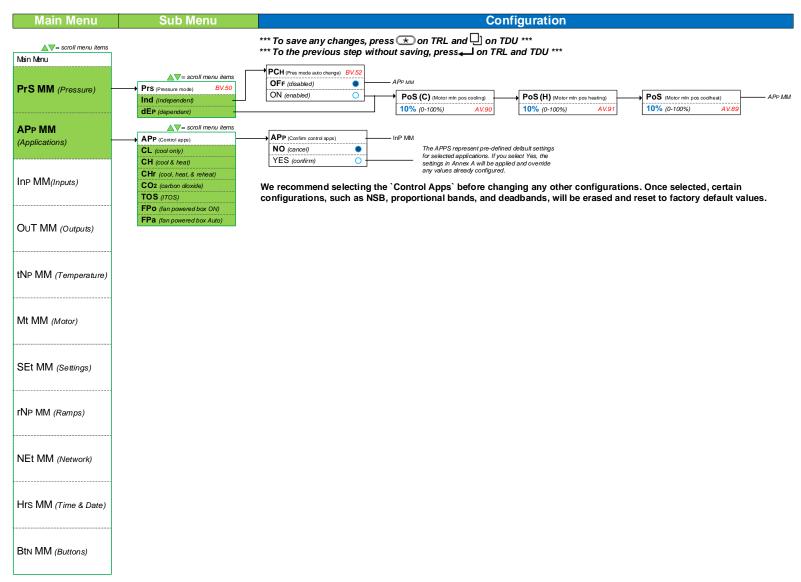


Note: Prior to going into Programming Mode, remove the connection cable between the EVCB and the TRL/TDU and set the Mode Selection jumper (JP1) to PGM on the digital room sensor. Reestablish the connection in order to access the programming menus and to make any changes. Once all menu changes have been made, remove the connection cable again before setting jumper JP1 back to RUN, and then reconnect the cable to resume normal operation.



Pressure & Applications – Menu Overview (1 of 6)

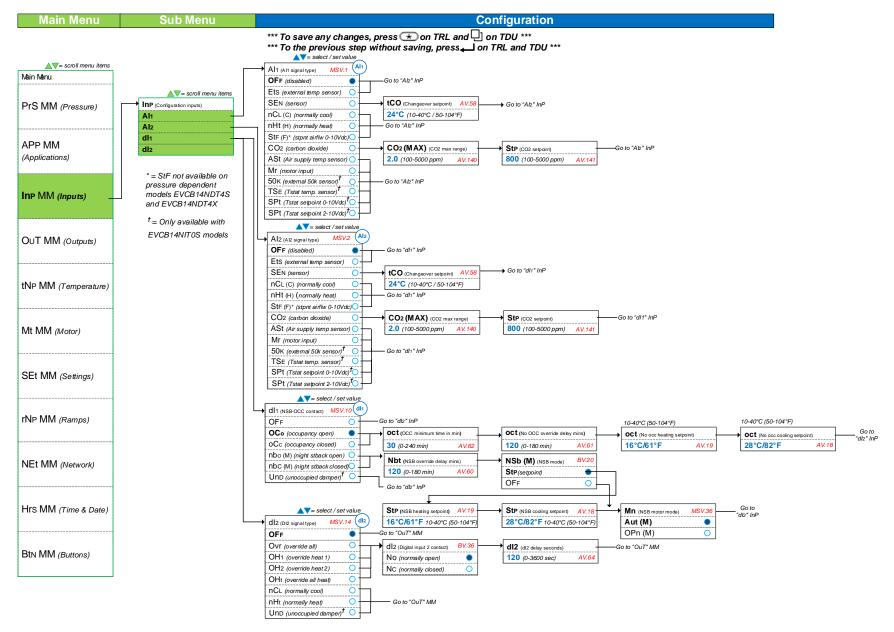
For a description of the default settings for each application refer to Annex A: Control Apps on page 23.



Inputs - Menu Overview (2 of 6)



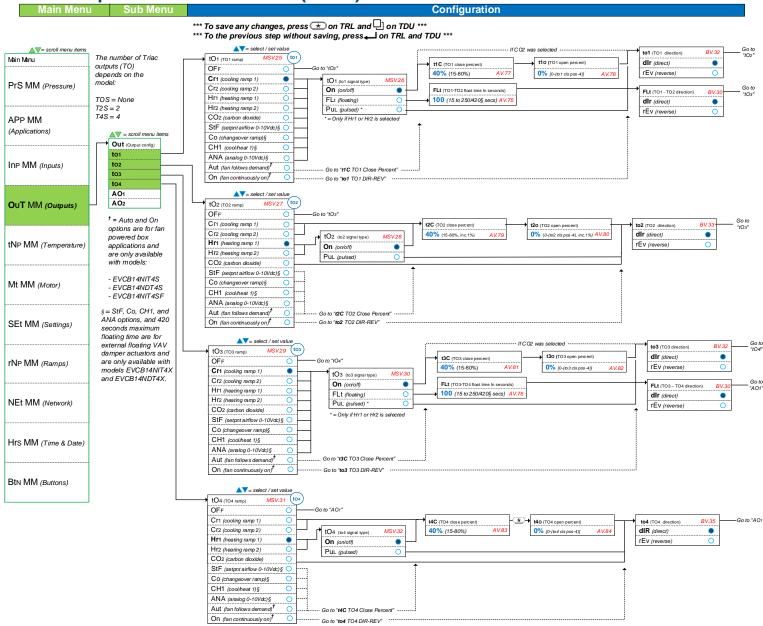
Specification and Installation Instructions





Specification and Installation Instructions

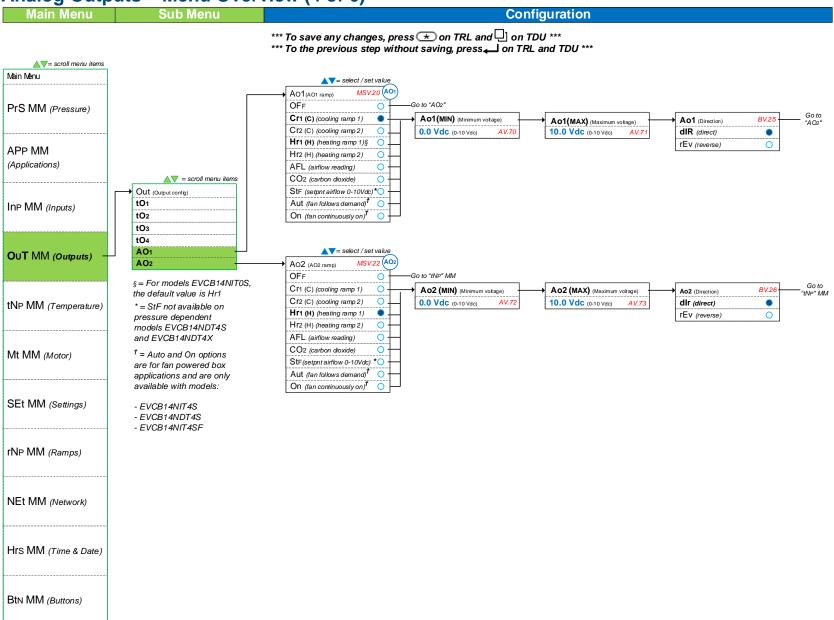
TRIAC Outputs - Menu Overview (3 of 6)





Specification and Installation Instructions

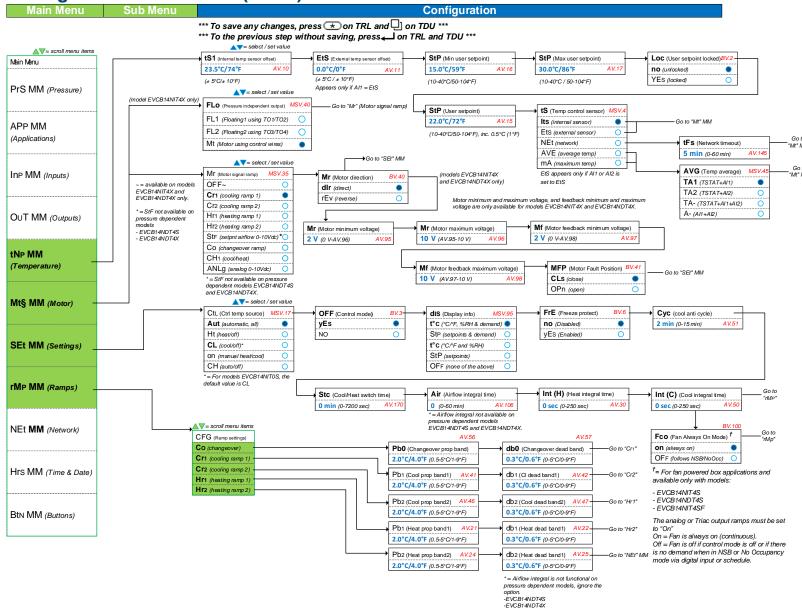
Analog Outputs - Menu Overview (4 of 6)





Specification and Installation Instructions

Settings – Menu Overview (5 of 6)





Specification and Installation Instructions

Settings – Menu Overview (6 of 6)

Sub Menu Main Menu Configuration *** To save any changes, press 🛨 on TRL and 🕘 on TDU *** *** To the previous step without saving, press on TRL and TDU *** ▲▼= scroll menu items Main Menu PrS MM (Pressure) APP MM (Applications) ▲▼= select / set value nEt (Network choice) bAc (BACnet) -Go to "Abr" (BACnet auto baud rate) Md (Modbus) 0 -Go to "Abr" (Modbus auto baud rate) Inp MM (Inputs) ▲▼= select / set value Go to CFG (Modbus comport config) MA (Modbus address) "HrS" Abr (Modbus auto baud rate) bAu (Modbus baud rate) ▲▼= scroll menu items 57.6k (9.6k, 19.2k, 38.4, 57.6k) nP2 (no parity, 2 stop bits) 1 (1-246) No (Manual) OUT MM (Outputs) nEt (Network config) Modifiable only if Auto Baud Rate EP1 (even parity, 1 stop bit) Modifiable only if all DS2 DIP Yes (Automatic) • set to "No". switches are set to OFF tYP (Type) OP1 (odd parity, 1 stop bit) ▲▼= select / set value Md (Modbus) Go to "CPY" bAC (BACnet) M (MSTP MAX master) Abr (BACnet auto baud rate) bAu (Bacnet baud rate) Add (MSTP MAC address) 1000 tNP MM (Temperature) CPY (copy configuration) No (Manual) 76.8k (9.6k, 19.2k, 38.4, 76.8k) 0 (0-254) 127 (1-127) Yes (Automatic) • Modifiable only if Auto Baud Rate Modifiable only if all DS2 DIP If type = bAC, menu contains set to "No" switches are set to OFF. "tYpe", "bAC" and "CPY" ▲▼= select / set value Go to "Hrs" MM If type = Md, menu contains "tYpe Mt MM (Motor) Cpy (Confirm copy config) BV.90 Copy Config Add (Start address) Add (End address) 0 (0-254: max=start + 63) AV.166 nO Copy (cancel) in (in progress) 0 (0-254, inc.1) YES Copy (confirm) SCd (Config succeed) SEt MM (Settings) (done) Refer to Copy Config Annnex for a complete list of messages and rNP MM (Ramps) ▲▼= select / set value Hrs (Hours) MI (Minutes) yr (Year) Local Date tF (Set time display format) 24 (24-hour format) 12 (1-24 or 1-12 am/pm) 00 (00-59) **15** (15-99) NEt MM (Network) 12 (AM/PM format) O dAy Local Date Mo (Month) Local Date —Go to "BtN" 1 (1-12) 1 (1-31) Hrs MM (Time & Date) ▲▼= select / set value BLK (Bottom left key locked) ULK (Upper left key locked) AK (Arrows key locked) -Go to "PrS" NO NO NO • Btn MM (Buttons) YES YES YES 0 0



Specification and Installation Instructions

Operation Menus

This menu is accessible through normal operation mode. The Mode Selector jumper (JP1) of the digital room sensor must be set to the "RUN" position (Operation Mode). Refer to Wiring on page 10.

Note: Since the action buttons are different on TRL and TDU digital room sensor series, both buttons have been included in the instructions. Refer to the Action Buttons on Digital Room Sensor section to know and use the button as available on your digital room sensor.

1. Press the [🖈 / 🗓] and [🚽] buttons simultaneously for 5 seconds. The "ENTER PRSSWORD" screen appears.

[50 to 104°F]

- 2. Enter the password within 1 minute by using the arrow keys to increase or decrease the value and the [🛨 / 🗓] and [🚽] buttons to toggle between the digits.
 - b. Password 372 = Temperature Offset Menu
 - c. Password 637 = Network Settings Menu
 - d. Password 757 = Airflow Balance Mode
- 3. If you enter the wrong password, the digital room sensor displays "**Eror**" and returns to Operation Mode. The digital room sensor will return to normal mode if you navigate through the entire menu and do not make any selection, or if you do not press any key for 5 minutes. The changed values will be saved automatically.

Menu 372 - Temperature Offset

1. "757" (temperature sensor offset)

Range: 10 to 40°C

Offset: $Max \pm 5^{\circ}C$

Increment: 0.1°C [0.2°F]

Compare the displayed temperature reading with a known value from a thermometer. To offset or calibrate the sensor, use the arrows key to set the desired temperature reading. This is useful for digital room sensors installed in areas where the temperature read is slightly different than the room's actual temperature. For example, a digital room sensor placed right under the air diffuser.

If the digital room sensor is set to use an external temperature sensor (EtS), the digital room sensor displays "OFF".

2. "ETS" (external temperature sensor offset)

Range: 0 to 50°C [41 to 122°F]

Offset: Max ± 5°C

Increment: 0.1°C [0.2°F]

This option appears if you've set one of the analog inputs to **EtS** (External temperature sensor). When the digital room sensor is connected to the appropriate analog input, the display shows the temperature read by the external temperature sensor. Adjust the offset by comparing it with a known value (e.g. thermometer). If the sensor is not connected or short circuited, then the unit displays the sensor's limit.

3. "PR5" (input 3 reading)



Range: 250mV (0") to 4000mV (1")

Displays the voltage output value in mV of the pressure sensor. Does not appear for EVCB14NDT4S and EVCB14NDT4X (pressure dependant) models.

4. "PR5 I'III" (input 3 minimum reading)

Range: 10mV to 180mV

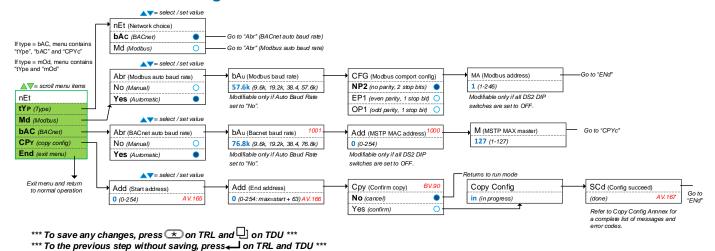
Default: 60mV

This setting represents the deadband of the pressure sensor in mV. For advanced users or special applications only. We recommend that you use the default setting of 60mV. Does not appear for EVCB14NDT4S and EVCB14NDT4X (pressure dependant) models.



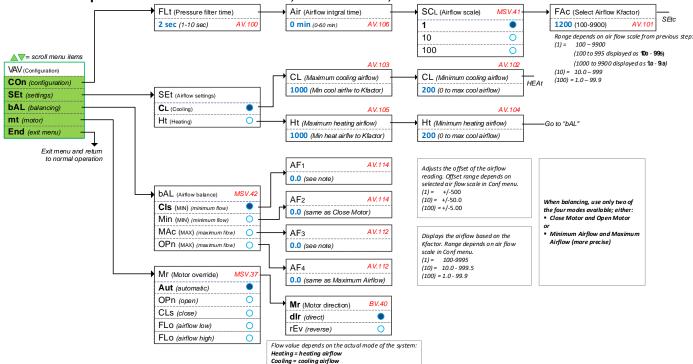
Specification and Installation Instructions

Menu 637 - Network Settings



Menu 757 - Airflow Balance Mode

Pressure Independent: models EVCB14NIT0S, EVCB14NIT2S, EVCB14NIT4X and EVCB14NIT4S

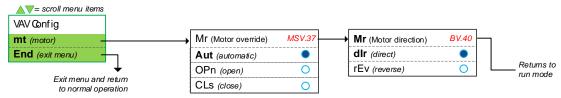


*** To save any changes, press on TRL and on TDU ***
*** To the previous step without saving, press on TRL and TDU ***



Note: Refer to EVCB-Airflow Balance Instructions on Neptronic website for further information on the airflow balancing function.

Pressure Dependent: models EVCB14NDT4S, EVCB14NDT4X or other models if in pressure dependent mode



*** To save any changes, press lacktriangledown on TRL and lacktriangledown on TDU ***

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^{***} To the previous step without saving, press on TRL and TDU ***



Specification and Installation Instructions

Reset to Factory Default Settings

<u>^</u>	

This will erase all actual configurations and replace them with the factory default settings.

- 1. The Mode Selector jumper (JP1) of the digital room sensor must be set to the "RUN" position (Operation Mode). Refer to Wiring on page 10.
- 2. During the power up sequence of the controller and digital room sensor, press and hold both the ◀ and ▼buttons.
- 3. The "ENTER PRSSWORD" screen appears. Enter 372 within 1 minute by using the arrow keys to increase or decrease the value and the [🛨 / 🗓] and 🟓 buttons to toggle between the digits.

4. Use the arrow buttons to select YES and then press [🛨 / 🗓].

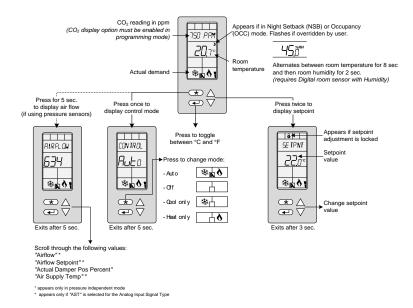


Specification and Installation Instructions

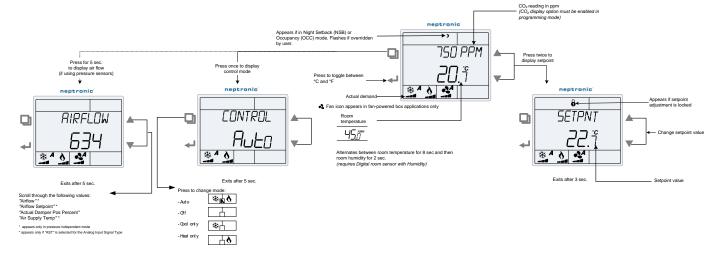
Operation Mode

The Mode Selector Jumper (JP1) of the digital room sensor must be set to the "RUN" position (Operation Mode). Refer to Wiring on page 10.

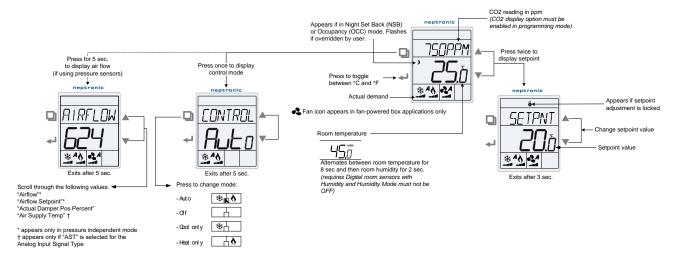
TRL54



TDU10 / TDU40 / TDU70 Series



TDU00 / TDU30 / TDU60 Series



neptronic^{*}

Networkable VAV Controller

Specification and Installation Instructions

Power Up

Upon power up, the LCD illuminates and all segments appear for 2 seconds. The digital room sensor then displays its current version of the digital room sensor for 2 seconds followed by the current version of the controller for 2 seconds. Pressing any key on the digital room sensor illuminates the LCD for 4 seconds.

CO₂ (Digital Room Sensors with CO₂)

If enabled via the configuration menu, the digital room sensor displays the CO₂ reading on the first line above the temperature reading. If CO₂ display is enabled, the time will not be displayed.

Temperature Display and Setpoint

If enabled in the "Display Info" menu (see Settings – Menu Overview (5 of 6) on page 17), the digital room sensor displays the temperature reading. If the sensor is disconnected or short circuited, then the unit displays the sensor's limit. To toggle the temperature scale between °C and °F, press the → button. To display the setpoint, press the ▲ or ▼ key twice. The setpoint appears for 5 seconds. To adjust the setpoint, press the arrow keys while the temperature is displayed. If the setpoint adjustment has been locked "Setpnt Locked", the lock ❸ symbol appears.

Humidity

If enabled in the "Options" menu (see Settings – Menu Overview (6 of 6) on page), the digital room sensor displays the temperature reading for 8 seconds and then displays the humidity reading for 2 seconds. If the sensor is disconnected or short circuited, then the unit displays the sensor's limit.

Air Flow and Air Supply Temperature*

Control Mode

To access the Control Mode, press the [J] button. The Control Mode appears for 5 seconds. Press the [J] button to scroll through the following control modes. These options can vary depending on the options selected in "Temp Control Mode" and "Enable OnOff Control Mode".

- Auto (Automatic Cooling or Heating)
- OFF (if it is not disabled in Programming Mode)
- Cooling only (on, with cooling symbol)
- Heating only (on, with heating symbol)

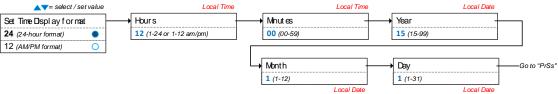
Night Set Back (NSB) or Occupancy Mode

This function is only available if you set DI1 to **nSb** (Night set back contact) or **Occ** (occupancy mode). If the DI1 contact is triggered, the digital room sensor enters NSB or No Occupancy Mode (the) symbol appears) and uses the NSB or OCC heating and cooling setpoints.

If not locked, you can override the night set back or no occupancy mode for a predetermined period by pressing any of the 4 buttons. During the override period the $^{\circ}$ symbol will flash. If the $^{\circ}$ symbol does not flash, the override period is finished or the night set back or no occupancy override has been locked in programming mode.

Set Time and Date

- 1. Ensure that JP1 on the digital room sensor is set to run.
- 2. Press and hold the button for 5 seconds.
- 3. Use the arrow keys to set the desired value. Press the [*/ *!] button to save and got to the next step. Press the button to go to the previous step without saving.



^{***} To save any changes, press 🛨 on TRL and 🗓 on TDU ***

Note: Time will only be displayed on the TDU when the Bacnet scheduler is active. In order to achieve this, set the proper BACnet Object present value to Yes (1): **EVCB BV.70 – Cfg ActiveSchedule.**

^{***} To the previous step without saving, press on TRL and TDU ***



Specification and Installation Instructions

Annex A: Control Apps

Refer to Pressure & Applications – Menu Overview (1 of 6) on page 13 for more information. The available **Control Apps** vary according to the model.

Description Description	CL (cool only)	CLHt (cool/heat)	CHrH (cool/heat/reheat)	CO2 (CO2)	ITOS (ITOS)	FPbo (fan powered ON)	FPbA (fan powered Auto)
Min. Setpoint	20°C (68°F)	20°C (68°F)	20°C (68°F)	20°C (68°F)	15°C (59°F)	15°C (59°F)	15°C (59°F)
Max. Setpoint	28°C (82°F)	28°C (82°F)	28°C (82°F)	28°C (82°F)	30°C (86°F)	30°C (86°F)	30°C (86°F)
Changeover Setpnt	24°C (75°F)	20°C (68°F)	20°C (68°F)	20°C (68°F)	24°C (75°F)	24°C (75°F)	24°C (75°F)
TO1 Ramp	HR1	CR1	HR1	CR1	OFF	HR1	HR1
TO1 Signal Type	On/Off	On/Off	On/Off	On/Off	On/Off	On/Off	On/Off
TO1 Close Pos.	40%	40%	40%	40%	40%	35%	35%
TO1 Open Pos.	0%	0%	0%	0%	0%	0%	0%
TO2 Ramp	HR1	HR1	HR1	CO2	OFF	HR1	HR1
TO2 Signal Type	Pulse	On/Off	Pulse	On/Off	On/Off	On/Off	On/Off
TO2 Close Pos.	40%	40%	40%	40%	40%	70%	70%
TO2 Open Pos.	0%	0%	0%	0%	0%	35%	35%
TO3 Ramp	HR2	CR2	HR2	HR1	OFF	Fan ON	Fan Auto
TO3 Signal Type	On/Off	On/Off	On/Off	On/Off	On/Off	On/Off	On/Off
TO3 Close Pos.	40%	40%	40%	40%	40%	40%	40%
TO3 Open Pos.	0%	0%	0%	0%	0%	0%	0%
TO4 Ramp	HR2	HR2	HR2	HR1	OFF	HR1	HR1
TO4 Signal Type	Pulse	On/Off	Pulse	On/Off	On/Off	On/Off	On/Off
TO4 Close Pos.	40%	40%	40%	40%	40%	40%	40%
TO4 Open Pos.	0%	0%	0%	0%	0%	0%	0%
Motor Ramp	CR1	COr	COr	COr	CR1	CR1	COr
AO1 ramp	HR1	CR1	HR1	CR1	HR1	HR1	HR1
AO2 Ramp	HR2	HR1	HR2	HR1	OFF	HR2	Fan Auto
Al1 Input	OFF	SENS	SENS	SENS	OFF	OFF	SENS
Al2 Input	OFF	OFF	OFF	CO2	OFF	OFF	OFF
DI1 Input	nSb.o	nSb.o	nSb.o	Occ.o	Occ.o	nSb.o	nSb.o
Heat Prop Band 2	2°C (4°F)	2°C (4°F)	2°C (4°F)	2°C (4°F)	2°C (4°F)	1°C (2°F)	1°C (2°F)
Heat Deadband 2	1.3°C (2.6°F)	1.3°C (2.6°F)	1.3°C (2.6°F)	1.3°C (2.6°F)	0.3°C (0.6°F)	1.3°C (2.6°F)	1.3°C (2.6°F)
Cool Deadband 2	1.3°C (2.6°F)	1.3°C (2.6°F)	1.3°C (2.6°F)	1.3°C (2.6°F)	0.3°C (0.6°F)	0.3°C (0.6°F)	0.3°C (0.6°F)

Legend

Grey Text = Standard default value

Bold Text = Special default value for selected application

HR = Heating ramp
CR = Cooling ramp
COr = Changeover ramp

SENS = Changeover temperature sensor Fan ON = Fan powered box in continuous mode

Fan Auto = Fan powered box in automatic mode (follows demand)

nSb.o = Night Set Back (normally open)
Occ.o = Occupancy mode (normally open)

TO = TRIAC output
AO = Analog output
AI = Analog input
DI = Digital input

Notes			







Recycling at end of life: please return this product to your Neptronic local distributor for recycling. If you need to find the nearest Neptronic authorized distributor, please consult **www.neptronic.com**.



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